

## Getting started with AT32F403AVGT7

## Introduction

AT-START-F403A is designed to help you explore the high-performance features of the 32-bit microcontroller, AT32F403A embedded with ARM Cortex®-M4F with FPU, and help develop your applications.

AT-START-F403A is an evaluation board based on AT32F403AVGT7 chip with LED indicators, buttons, an USB micro-B connector, Arduino<sup>TM</sup> Uno R3 extension connector and an expanded 16 MB SPI Flash memory. This evaluation board embeds debugging/programming tool AT-Link-EZ without the need of other development tools.



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## 1 Overview

### 1.1 Features

AT-START-F403A has the following characteristics:

- AT-START-F403A has an on-board AT32F403AVGT7 microcontroller that embeds ARM Cortex®-M4F, 32-bit processor, 1024 KB Flash memory and 96+128 KB SRAM, LQFP100 packages.
- On-board AT-Link connector:
  - The on-board AT-Link-EZ can be used for programming and debugging (AT-Link-EZ is a simplified version of AT-Link, and does not support offline mode)
  - If AT-Link-EZ is separated from this board by bending over along the joint, AT-START-F403A can be connected to an independent AT-Link for programming and debugging
- On-board 20-pin ARM standard JTAG connector (with a JTAG/SWD connector for programming/debugging)
- 16 MB SPI Flash EN25QH128A is used as an expanded Flash memory Bank 3
- Various power supply methods:
  - Through the USB bus of AT-Link-EZ
  - Through the USB bus (V<sub>BUS</sub>) of AT-START-F403A
  - External 7~12 V power supply (VIN)
  - External 5 V power supply (E5V)
  - External 3.3 V power supply
- 4 x LED indicators:
  - LED1 (red) used for 3.3 V power-on
  - 3 x user LED indicators: LED2 (red), LED3 (yellow) and LED4 (green)
- 2 x buttons (user button and reset button)
- 8 MHz HSE crystal
- 32.768 kHz LSE crystal
- USB micro-B connector
- Various extension connectors can be quickly connected into a prototype board and easy to explore:
  - Arduino<sup>™</sup> Uno R3 extension connector
  - LQFP100 I/O extension connector

#### 1.2 Definition of terms

- Jumper JPx ON
  - Jumper installed
- Jumper JPx OFF
  - Jumped not installed
- Resistor Rx ON
  - Short by solder or  $0\Omega$  resistor
- Resistor Rx OFF
  - Open



## 2 Quick start

AT-START-F403A is a low-cost and easy-to-use development kit that is designed for quickly evaluating and using the high-performance AT32F403A microcontrollers to develop applications.

#### 2.1 Get started

Configure the AT-START-F403A board in the following order to start the application:

1. Check the Jumper position on the board:

JP1 is connected to GND or OFF (BOOT0 is 0, and BOOT0 has an pull-down resistor in the AT32F403AVGT7);

JP4 optional or OFF (BOOT1 is in any state);

JP8 one-piece jumper is connected to I/O on the right.

- 2. Connect the AT-START-F403A board to the PC through an USB cable (Type A to micro-B), and the board will be powered via AT-Link-EZ USB connector CN6. LED1 (red) is always on, and the other three LEDs (LED2 to LED4) start to blink in turn.
- 3. After pressing the USER button (B2), the blink frequency of three LEDs are changed.

## 2.2 Toolchains supporting AT-START-F403A

■ ARM® Keil®: MDK-ARM™

IAR™: EWARM



## 3 Hardware and layout

AT-START-F403A board is designed around an AT32F403AVGT7 microcontroller in LQFP100 package.

*Figure 1* shows the connections between AT-Link-EZ, AT32F403AVGT7 and their peripherals (buttons, LEDs, USB, SPI Flash memory and extension connectors)

Figure 2 and Figure 3 show these features on the AT-Link-EZ and AT-START-F403A board.

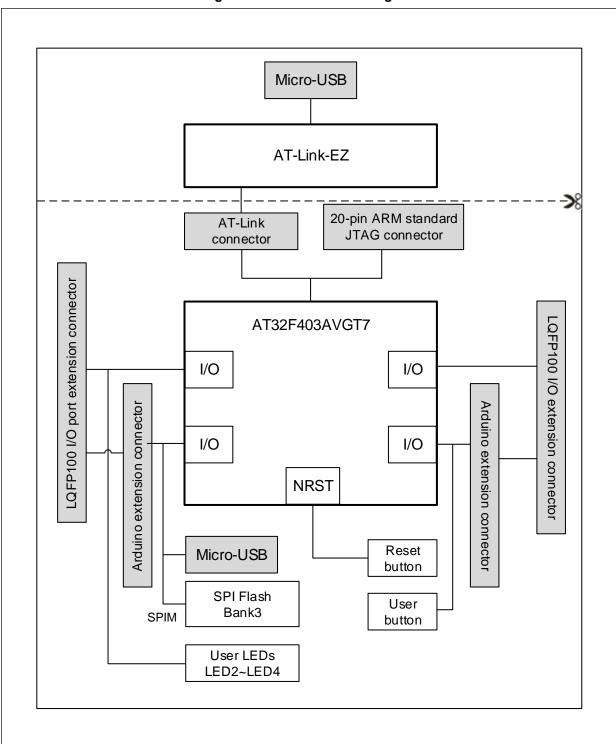


Figure 1. Hardware block diagram



Figure 2. Top layer

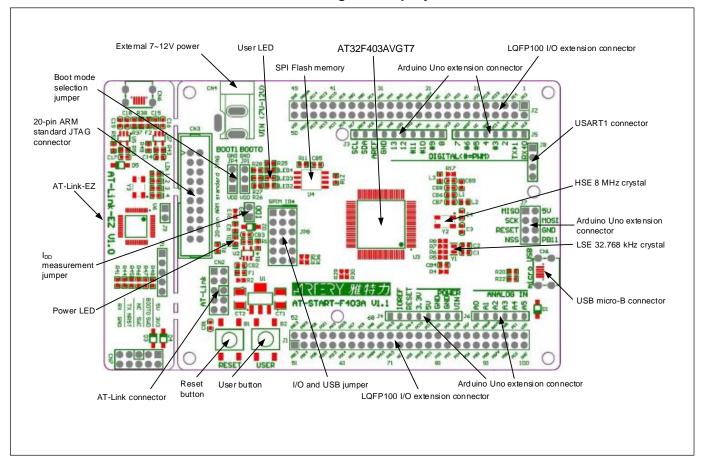
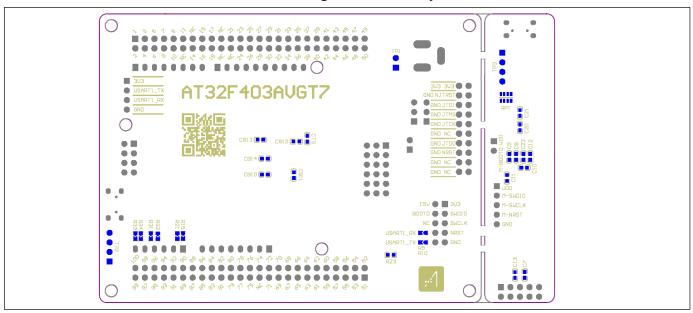


Figure 3. Bottom layer





## 3.1 Power supply selection

The 5 V power supply of AT-START-F403A can be provided through a USB cable (either through the USB connector CN6 on the AT-Link-EZ or USB connector CN1 on the AT-START-F403A), or through an external 5 V power supply (E5V), or by an external 7~12 V power supply (VIN) via 5V voltage regulator (U1) on the board. In this case, the 5 V power supply provides the 3.3 V power required by the microcontrollers and peripherals by means of the 3.3 V voltage regulator (U2) on the board.

The 5 V pin of J4 or J7 can also be used as an input power source. The AT-START-F403A board must be powered by a 5 V power supply unit.

The 3.3 V pin of J4 or the VDD pin of J1 and J2 can also be directly used as 3.3 V input power supply. AT-START-F403A board must be powered by a 3.3 V power supply unit.

Note: Unless 5 V is provided through the USB connector (CN6) on the AT-Link-EZ, the AT-Link-EZ will not be powered by other power supply methods.

When another application board is connected to J4, the VIN, 5 V and 3.3 V pins can be used as output power; J7 5V pin used as 5 V output power; the VDD pin of J1 and J2 used as 3.3 V output power.

#### 3.2 IDD

In the event of JP3 OFF (symbol IDD) and R13 OFF, it is allowed to connect an ammeter to measure the power consumption of AT32F403AVGT7.

• JP3 OFF, R13 ON:

AT32F403AVGT7 is powered. (Default setting and JP3 plug is not mounted before shipping)

• JP3 ON, R13 OFF:

AT32F403AVGT7 is powered.

• JP3 OFF, R13 OFF:

An ammeter must be connected to measure the power consumption of AT32F403AVGT7 (if there is no ammeter, the AT32F403AVGT7 cannot be powered).

## 3.3 Programming and debugging

#### 3.3.1 Embedded AT-Link-EZ

The evaluation board embeds Artery AT-Link-EZ programming and debugging tool for users to program/debug the AT32F403AVGT7 on the AT-START-F403A board. AT-Link-EZ supports SWD interface mode and supports a set of virtual COM ports (VCP) to connect to the USART1\_TX/USART1\_RX (PA9/PA10) of AT32F403AVGT7. In this case, PA9 and PA10 of AT32F403AVGT7 will be affected by AT-Link-EZ as follows:

- PA9 is weakly pulled up to high level by the VCP RX pin of AT-Link-EZ;
- PA10 is strongly pulled up to high level by the VCP TX pin of AT-Link-EZ

The user can set R9 and R10 OFF, then the use of PA9 and PA10 of AT32F403AVGT7 is not subject to the above restrictions.

Please refer to <u>AT-Link User Manual</u> for complete details on the operations, firmware upgrade and precautions of AT-Link-EZ.

The AT-Link-EZ PCB on the evaluation board can be separated from AT-START-F403A by bending over along the joint. In this case, AT-START-F403A can still be connected to the CN7 of AT-Link-EZ through CN2 (not mounted before shipping), or can be connected with another AT-Link to continue the programming and debugging on the AT32F403AVGT7.

## 3.3.2 20-pin ARM® standard JTAG connector

AT-START-F403A also reserves JTAG or SWD general-purpose connectors as programming/debugging tools. If the user wants to use this interface to program and debug the AT32F403AVGT7, please separate the AT-Link-EZ from the board or set R41, R44 and R46 OFF, and connect the CN3 (not mounted before shipping) to the programming and debugging tool.

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#### 3.4 Boot mode selection

At startup, three different boot modes can be selected by means of the pin configuration.

Table 1. Boot mode selection jumper setting

| Jumper                       | Boot mode selection |       | Setting                             |  |
|------------------------------|---------------------|-------|-------------------------------------|--|
| dumper                       | BOOT1               | воото | Jetting                             |  |
| JP1 connected to GND or OFF; |                     |       | Boot from the internal Flash memory |  |
| JP4 optional or OFF          | Х                   | 0     | (Factory default setting)           |  |
|                              |                     |       |                                     |  |
| JP1 connected to VDD         | 0                   | 1     | Boot from the system memory         |  |
| JP4 connected to GND         | U                   | ı     |                                     |  |
| JP1 connected to VDD         | 1                   | 1     | Boot from SRAM                      |  |
| JP4 connected to VDD         | I                   |       |                                     |  |

### 3.5 External clock source

#### 3.5.1 HSE clock source

The 8 MHz crystal on the board is used as HSE clock source.

#### 3.5.2 LSE clock source

There are three hardware modes to set the external low-speed clock sources:

#### On-board crystal (default setting):

The 32.768 kHz crystal on the board is used as LSE clock source. The hardware setting must be: R6 and R7 ON, R5 and R8 OFF

#### Oscillator from external PC14:

External oscillator is injected from the pin-3 of J2. The hardware setting must be: R5 and R8 ON, R6 and R7 OFF.

#### • LSE not used:

PC14 and PC15 are used as GPIO. The hardware setting must be: R5 and R8 ON, R6 and R7 OFF.



#### 3.6 LED indicators

#### Power LED1

Red indicates that the board is powered by 3.3 V

#### User LED2

Red, connected to the PD13 pin of AT32F403AVGT7

#### User LED3

Yellow, connected to the PD14 pin of AT32F403AVGT7

#### User LED4

Green, connected to the PD15 pin of AT32F403AVGT7

### 3.7 Buttons

#### Reset button B1:

Connected to NRST to reset AT32F403AVGT7

#### User button B2:

It is, by default, connected to the PA0 of AT32F403AVGT7, and alternatively used as a wakeup button (R19 ON, R21 OFF); or connected to PC13 and alternatively used as TAMPER-RTC button (R19 OFF, R21 ON)

### 3.8 USB device

AT-START-F403A board supports USB full-speed device communication through an USB micro-B connector (CN1). V<sub>BUS</sub> can be used as 5 V power supply of AT-START-F403A board.

## 3.9 Connect to Bank3 of Flash memory via SPIM interface

The SPI Flash EN25QH128A on the board is connected to the AT32F403AVGT7 via SPIM interface and used as Bank 3 of expanded Flash memory.

When using the Bank 3 of the Flash memory via SPIM interface, the JP8 one-piece jumper, as shown in *Table 2*, should select the left SPIM side. In this case, PB1, PA8, PB10 PB11, PB6 and PB7 are not connected to the external LQFP100 I/O extension connector. These 6 pins are marked by adding [\*] after pin name of extension connector on the PCB silkscreen.

Table 2. GPIO and SPIM jumper setting

| Jumper                | Settings  |
|-----------------------|---|
| JP8 connected to I/O  | Use I/O function (Default setting before shipping). |
| JP8 connected to SPIM | Use the SPIM function                               |



## 3.10 $0 \Omega$ resistors

Table 3. 0  $\Omega$  resistor setting

| Resistors                       | State <sup>(1)</sup> | Description   |  |  |
|---------------------------------|----------------------|---|--|--|
|                                 | O.V.                 | When JP3 is OFF, 3.3V is connected to the microcontroller                                     |  |  |
| R13                             | ON                   | to provide power supply   |  |  |
| (Microcontroller power          |                      | When JP3 is OFF, 3.3V allows an ammeter to be connected                                       |  |  |
| consumption measurement)        | OFF                  | to measure the power consumption of microcontroller   |  |  |
|                                 |                      | (if no ammeter, the microcontroller cannot be powered)  |  |  |
| R4                              | ON                   | V <sub>BAT</sub> must be connected to VDD   |  |  |
| (V <sub>BAT</sub> power supply) | OFF                  | V <sub>BAT</sub> can be powered by the pin_6 V <sub>BAT</sub> of J2                           |  |  |
| D5 D0 D7 D0                     | OFF, ON, ON, OFF     | LSE clock source uses crystal Y1 on the board   |  |  |
| R5, R6, R7, R8<br>(LSE)         | ON, OFF, OFF, ON     | LSE clock source is from external PC14 or PC14 and PC15 are used as GPIO.                     |  |  |
| R17                             | ON                   | V <sub>REF+</sub> is connected to VDD   |  |  |
| (V <sub>REF+</sub> )            | OFF                  | V <sub>REF+</sub> is connected to the J2 pin_21 or of Arduino <sup>TM</sup> connector J3 AREF |  |  |
| R19, R21                        | ON, OFF              | User button B2 is connected to PA0  |  |  |
| (USER button B2)                | OFF, ON              | User button B2 is connected to PC13   |  |  |
|                                 | OFF, OFF             | When PA11 and PA12 are used as USB, they are not  |  |  |
| R29, R30                        |                      | connected to pin_20 and pin_21 of J1.   |  |  |
| (PA11, PA12)                    | ON, ON               | When PA11 and PA12 are not used as USB, they can be   |  |  |
|                                 | ON, ON               | connected to pin_20 and pin_21 of J1.   |  |  |
| R31, R32, R33, R34              | OFF, ON, OFF, ON     | Arduino <sup>™</sup> A4 and A5 are connected to ADC_IN11 and ADC_IN10                         |  |  |
| (Arduino™ A4, A5)               | ON, OFF, ON, OFF     | Arduino <sup>™</sup> A4 and A5 are connected to I2C1_SDA and I2C1_SCL                         |  |  |
| R35, R36                        | OFF, ON              | Arduino™ D10 is connected to SPI1_SS  |  |  |
| (Arduino™ D10)                  | ON, OFF              | Arduino <sup>™</sup> D10 is connected to PWM (TMR4_CH1)                                       |  |  |
|                                 | ON                   | USART1_RX of AT32F403AVGT7 is connected to VCP TX   |  |  |
| R9                              |                      | of AT-Link-EZ   |  |  |
| (USART1_RX)                     | OFF                  | USART1_RX of AT32F403AVGT7 is disconnected from   |  |  |
|                                 | Oll                  | VCP TX of AT-Link-EZ  |  |  |
|                                 | ON                   | USART1_TX of AT32F403AVGT7 is connected to VCP RX   |  |  |
| R10                             |                      | of AT-Link-EZ   |  |  |
| (USART1_TX)                     | OFF                  | USART1_TX of AT32F403AVGT7 is disconnected from   |  |  |
|                                 |                      | VCP RX of AT-Link-EZ  |  |  |

<sup>(1)</sup> The factory default Rx state is shown in BOLD.



### 3.11 Extension connectors

## 3.11.1 Arduino™ Uno R3 extension connector

Female plug J3~J6 and male J7 support standard Arduino<sup>™</sup> Uno R3 connectors. Most of the daughter boards designed around Arduino<sup>™</sup> Uno R3 are suitable for AT-START-F403A.

Note 1: The I/O ports of AT32F403AVGT7 are 3.3 V compatible with Arduino<sup>TM</sup> Uno R3, but 5V incompatible.

Note 2: Set R17 OFF if it is needed to supply power through the J3 pin\_8 AREF of AT-START-F403A to the  $V_{REF+}$  of AT32F403AVGT7 by means of Arduino<sup>TM</sup> Uno R3 daughter board.

Table 4. Arduino™ Uno R3 extension connector pin definition

| Connector                        | Pin    | Arduino  | AT32F403A                     | Functions                      |
|----------------------------------|--------|----------|-------------------------------|--------------------------------|
| Commedia                         | number | pin name | pin name                      | Tunotiono                      |
|                                  | 1      | NC       | -                             | -                              |
|                                  | 2      | IOREF    | -                             | 3.3V reference                 |
|                                  | 3      | RESET    | NRST                          | External reset                 |
| J4                               | 4      | 3.3V     | -                             | 3.3V input/output              |
| (Power supply)                   | 5      | 5V       | -                             | 5V input/output                |
|                                  | 6      | GND      | -                             | Ground                         |
|                                  | 7      | GND      | -                             | Ground                         |
|                                  | 8      | VIN      | -                             | 7~12V input/output             |
|                                  | 1      | A0       | PA0                           | ADC123_IN0                     |
|                                  | 2      | A1       | PA1                           | ADC123_IN1                     |
| J6                               | 3      | A2       | PA4                           | ADC12_IN4                      |
| (Analog input)                   | 4      | А3       | PB0                           | ADC12_IN8                      |
|                                  | 5      | A4       | PC1 or PB9 <sup>(1)</sup>     | ADC123_IN11 or I2C1_SDA        |
|                                  | 6      | A5       | PC0 or PB8 <sup>(1)</sup>     | ADC123_IN10 or I2C1_SCL        |
|                                  | 1      | D0       | PA3                           | USART2_RX                      |
|                                  | 2      | D1       | PA2                           | USART2_TX                      |
| IE.                              | 3      | D2       | PA10                          | -                              |
| J5                               | 4      | D3       | PB3                           | TMR2_CH2                       |
| (Logic input/output<br>low byte) | 5      | D4       | PB5                           | -                              |
| low byte)                        | 6      | D5       | PB4                           | TMR3_CH1                       |
|                                  | 7      | D6       | PB10                          | TMR2_CH3                       |
|                                  | 8      | D7       | PA8 <sup>(2)</sup>            | -                              |
|                                  | 1      | D8       | PA9                           | -                              |
|                                  | 2      | D9       | PC7                           | TMR3_CH2                       |
|                                  | 3      | D10      | PA15 or PB6 <sup>(1)(2)</sup> | SPI1_NSS or TMR4_CH1           |
| J3                               | 4      | D11      | PA7                           | TMR3_CH2 or SPI1_MOSI          |
| (Logic input/output              | 5      | D12      | PA6                           | SPI1_MISO                      |
| high byte)                       | 6      | D13      | PA5                           | SPI1_SCK                       |
| riigir byte)                     | 7      | GND      | -                             | Ground                         |
|                                  | 8      | AREF     | -                             | V <sub>REF+</sub> input/output |
|                                  | 9      | SDA      | PB9                           | I2C1_SDA                       |



| Connector | Pin<br>number | Arduino<br>pin name | AT32F403A<br>pin name | Functions       |
|-----------|---------------|---------------------|-----------------------|-----------------|
|           | 10            | SCL                 | PB8                   | I2C1_SCL        |
|           | 1             | MISO                | PB14                  | SPI2_MISO       |
|           | 2             | 5V                  | -                     | 5V input/output |
|           | 3             | SCK                 | PB13                  | SPI2_SCK        |
| J7        | 4             | MOSI                | PB15                  | SPI2_MOSI       |
| (Others)  | 5             | RESET               | NRST                  | External reset  |
|           | 6             | GND                 | -                     | Ground          |
|           | 7             | NSS                 | PB12                  | SPI2_NSS        |
|           | 8             | PB11                | PB11                  | -               |

<sup>(1)</sup>  $0 \Omega$  resistor setting is shown in *Table 3*.

## 3.11.2 LQFP100 I/O extension connector

The extension connector J1 and J2 can connect the AT-START-F403A to external prototype/packing board. The I/O ports of AT32F403AVGT7 are available on these extension connectors. J1 and J2 can also be measured with the oscilloscope, logic analyzer or voltmeter probe.

Note 1: Set R17 OFF if it is necessary to supply power through the J2 pin\_21 V<sub>REF+</sub> of AT-START-F403A with an external power supply,

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<sup>(2)</sup> SPIM must be disabled and JP8 one-piece jumper must select I/O side, otherwise PA8 and PB6 cannot be used.



### 4 Schematic

Figure 4. Schematic (AT-Link-EZ)

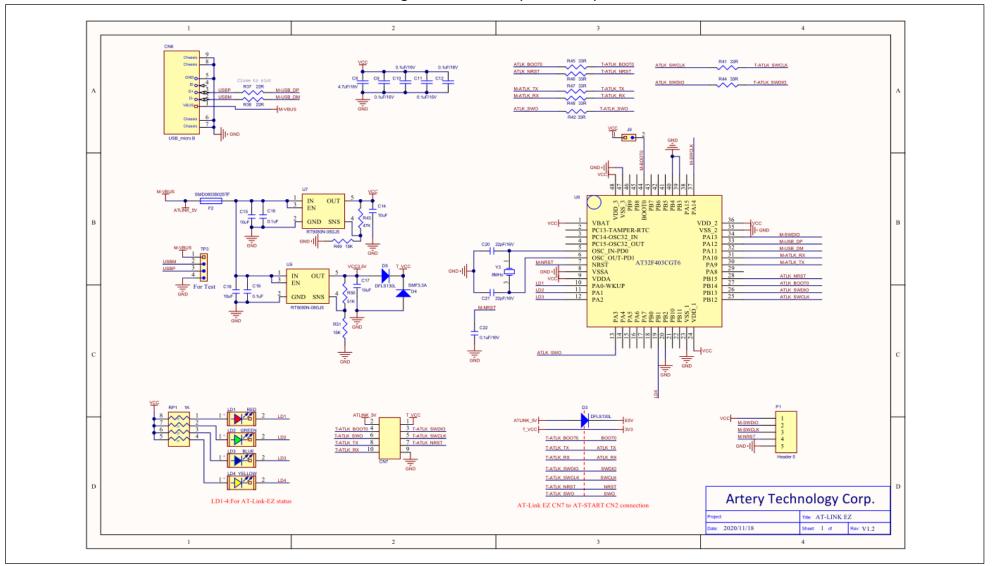
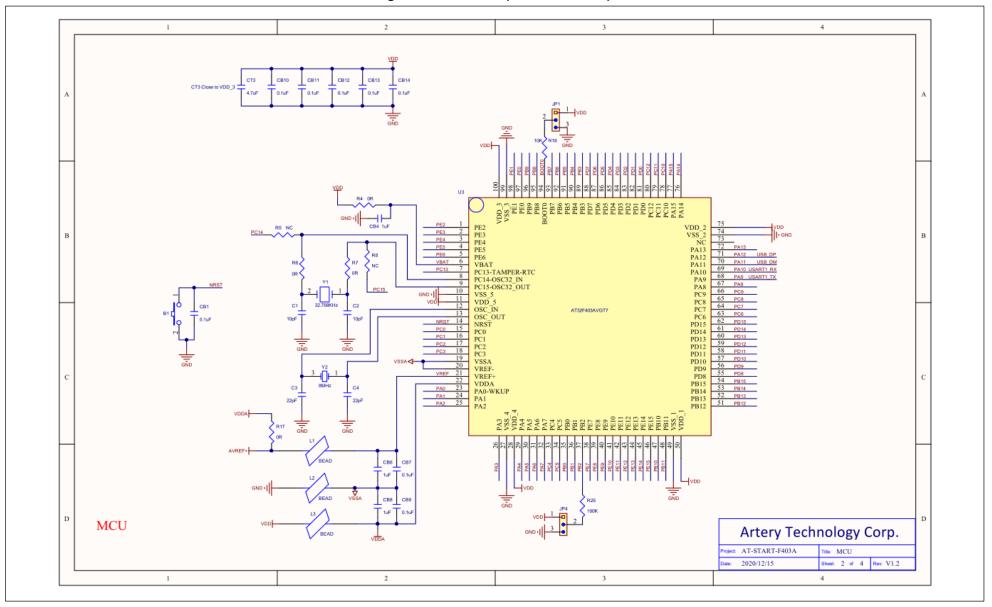




Figure 5. Schematic (microcontroller)





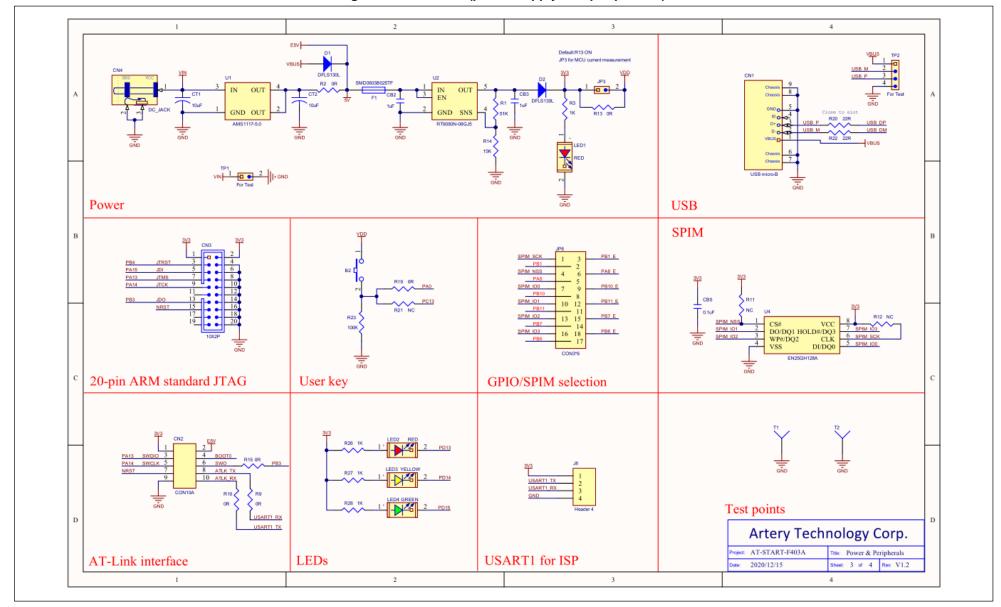


Figure 6. Schematic (power supply and peripherals)



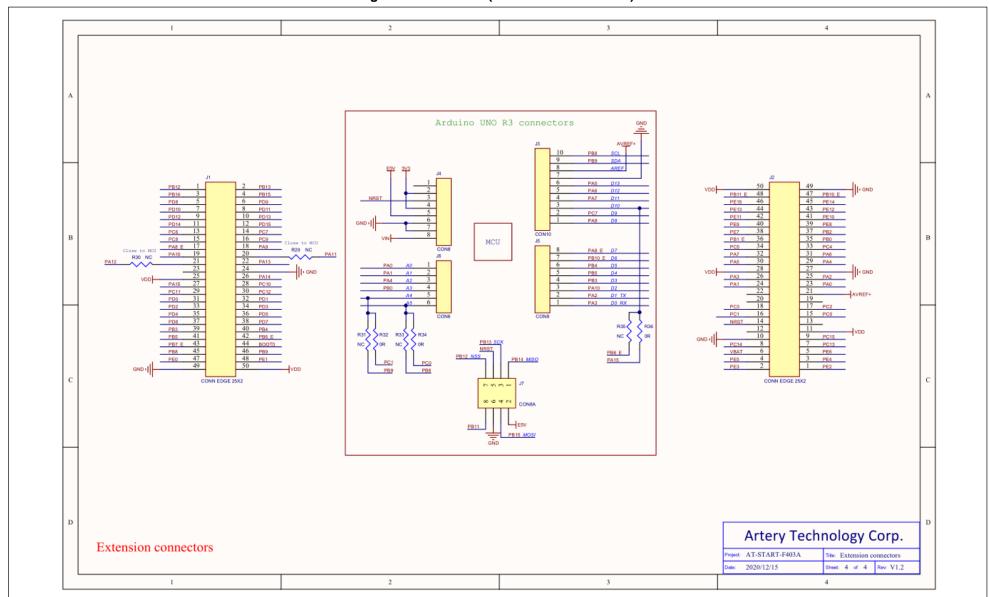


Figure 7. Schematic (extension connectors)



# 5 Revision history

**Table 5. Document revision history** 

| Date       | Revision | Changes   |
|------------|----------|---|
| 2020.2.14  | 1.0      | Initial release   |
| 2020.4.22  | 1.1      | Modified LED3 to yellow   |
|            |          | 1. Updated the revision code of this document to 3 digits, with the first two |
|            |          | for AT-START version, and the last one for the document version.              |
|            |          | 2. Updated AT-Link-EZ hardware to V1.2. Support SWO debug, added the          |
| 2020.12.15 | 1.20     | SWO description; and adjusted the CN7 signals, and corrected silkscreen in    |
|            |          | accordance with Artery development tools.                                     |
|            |          | 3. Modified CN2 silkscreen.   |
|            |          | Added GND test ring to facilitate measurement.                                |



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